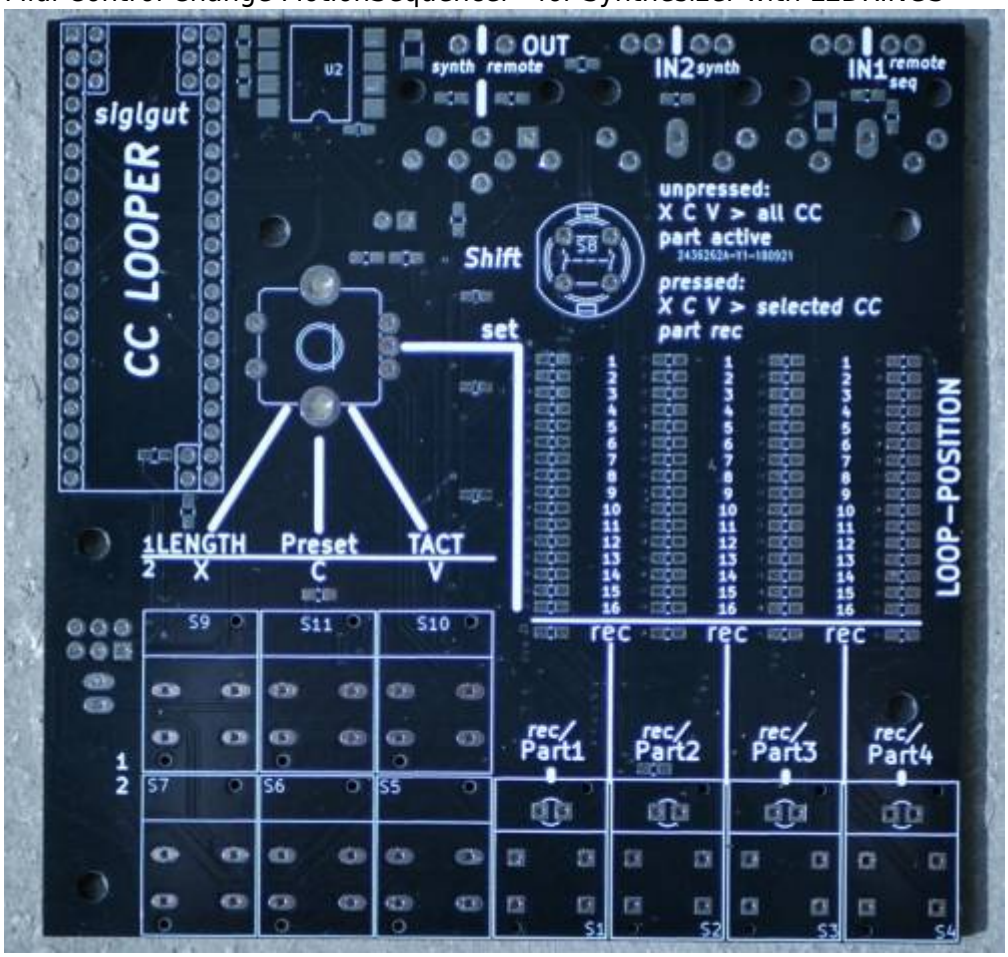
CC-Looper

CC-Automation
Midi Control Change MotionSequencer - for Synthesizer with LEDRINGS



Features

* 4Midichannels @ each 512Steps X 32th-looprate X 128 CCs
* only a few of the 128CC should be used @ once - 4x128xCCs @ 32th is Midi Data MESS and µC Death
* maybe only 256Steps, will depend on RAM…. RealWorld will tell
* each TRACK has a shared Track length for all its 128 CCs
* Copy, Paste, Clear: for the all 128CCs/or single CC
* There is no EDIT, you can clear a CC or Track and make a new Take
* ProgramChange Load and Store on microSD-Card, Load and Store are CC-Commands, so you can remote the device
* The Sequencer can be set to Tact Systems: 3/4 4/4 5/4 7/4 9/4 11/4 13/4

Hardware Requirements

External Requirement:(for example)

- You need a Synth with LEDRINGs - otherwise you have no Feedback and Overview - NordRack III is such one
- Melody/Clock Source with ProgramChange-Output: midibox_seq_v4l oops that dont do PC...
- Melody/Clock/CC Destination: NordRack III or any other Synth with Visual Feedback off CC-States

Midibox:

- dipcoref4 - this is the µC Brain for the Looper
- cc-looper - this is the UI-PCB of the Looper
- no other PCBs needet

- µSD-Card, formated with FAT32
- Soldering Iron - with a Dip that can Handle SMD-Parts, Wires, solder Paste for the µC....
- USB Power Supply with µUSB-Connector

Set

Cabeling

Midi IN1 »> MelodySequencer and Remote Devices
Midi IN2 »> Midi Out from Synthesizer - which sends out the Moved CCs
Midi OUT »> Midi IN of Synthesizer input (Automated CCs merged with mididata from Midi IN1)

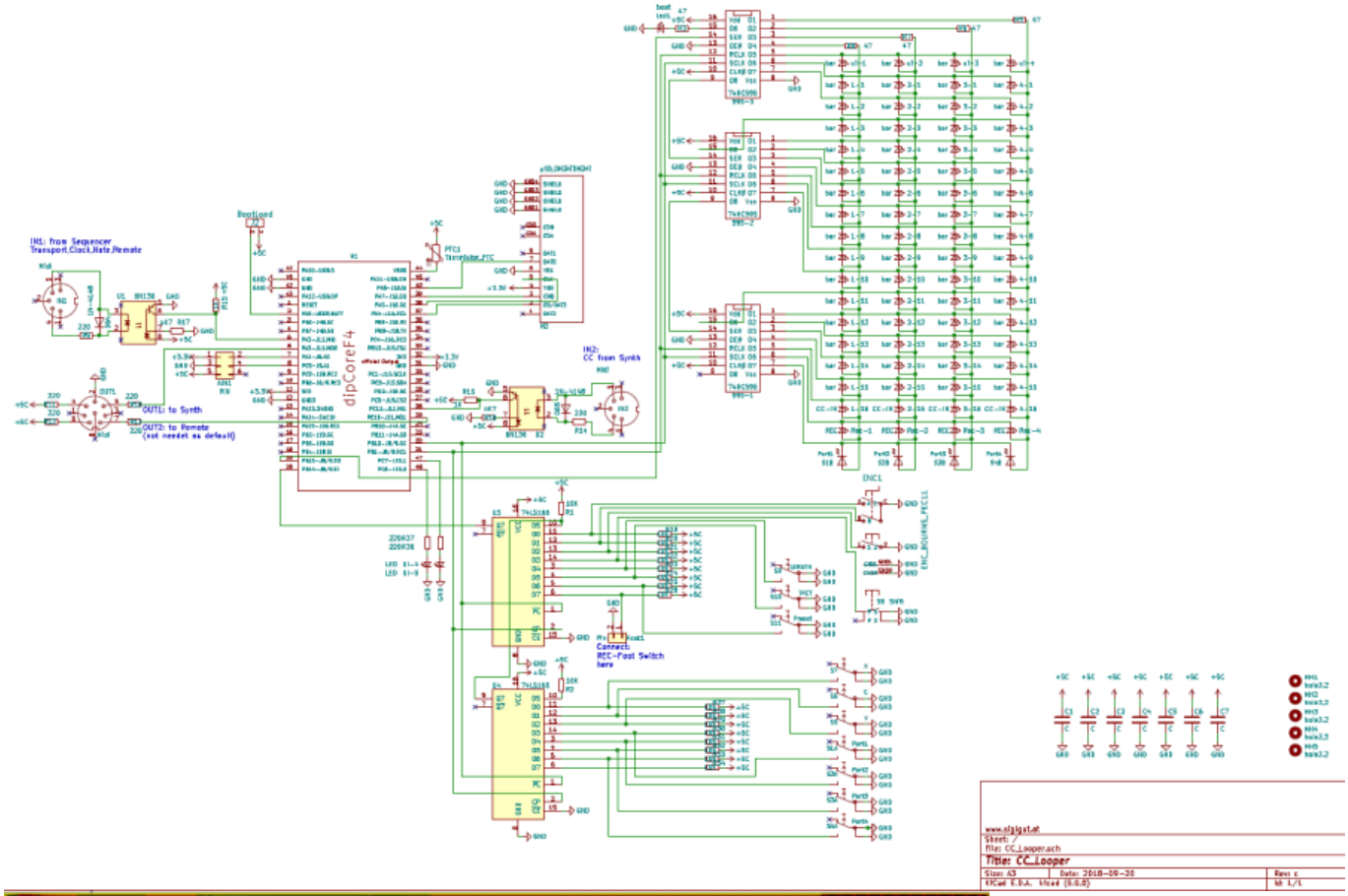
Software

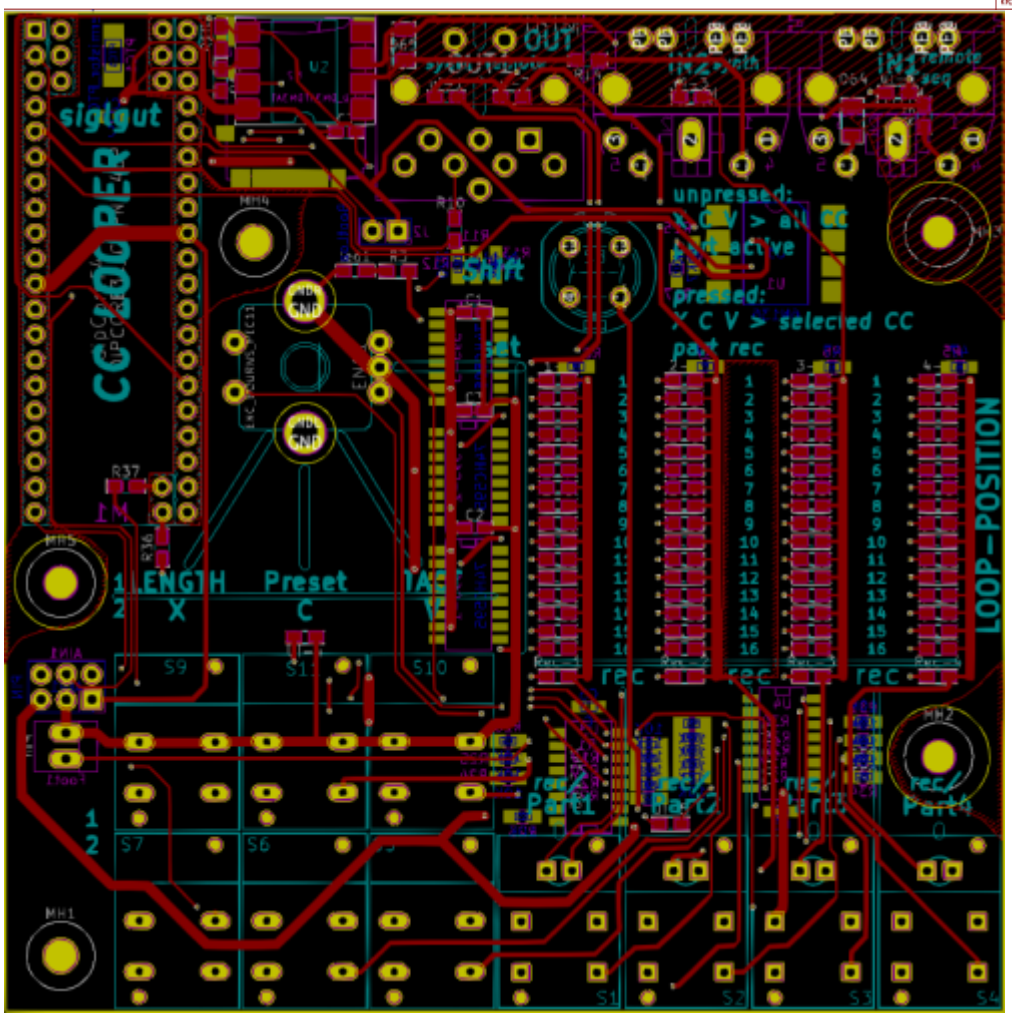
Firmware

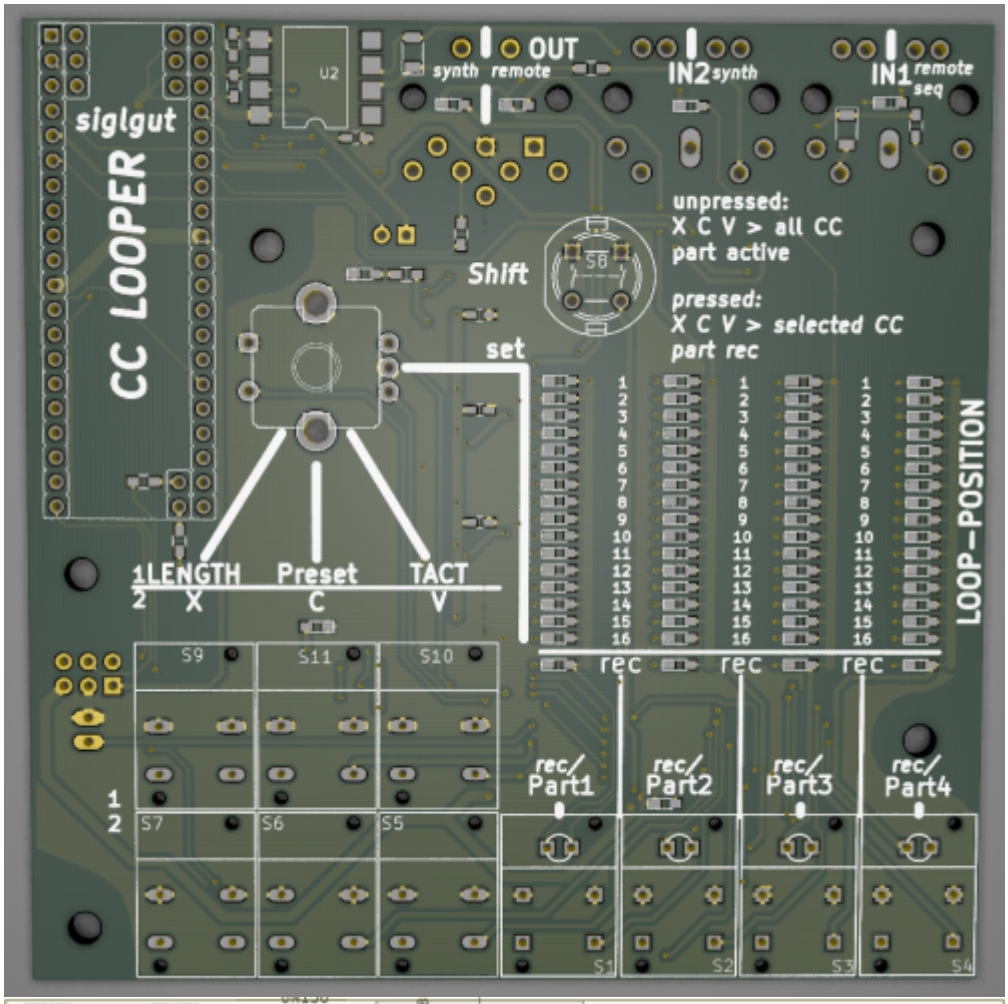


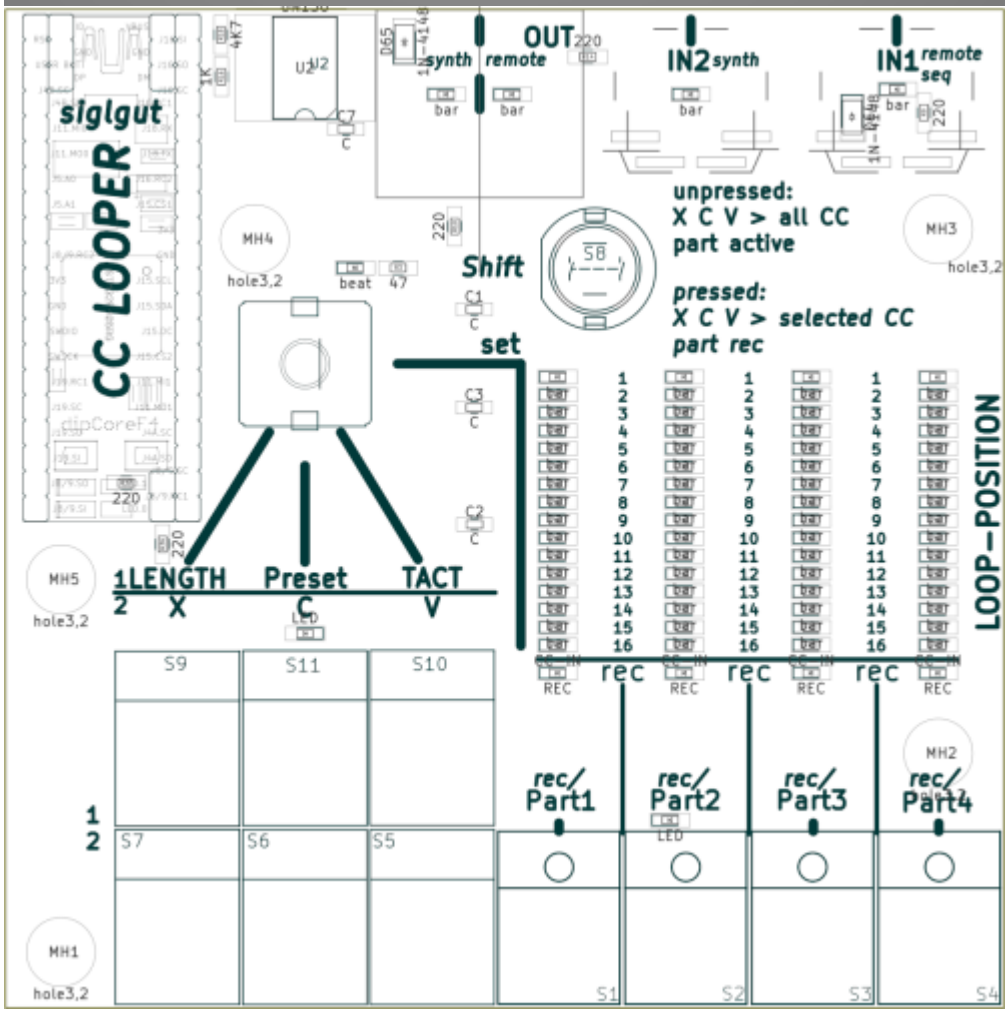
Firmware not made yet

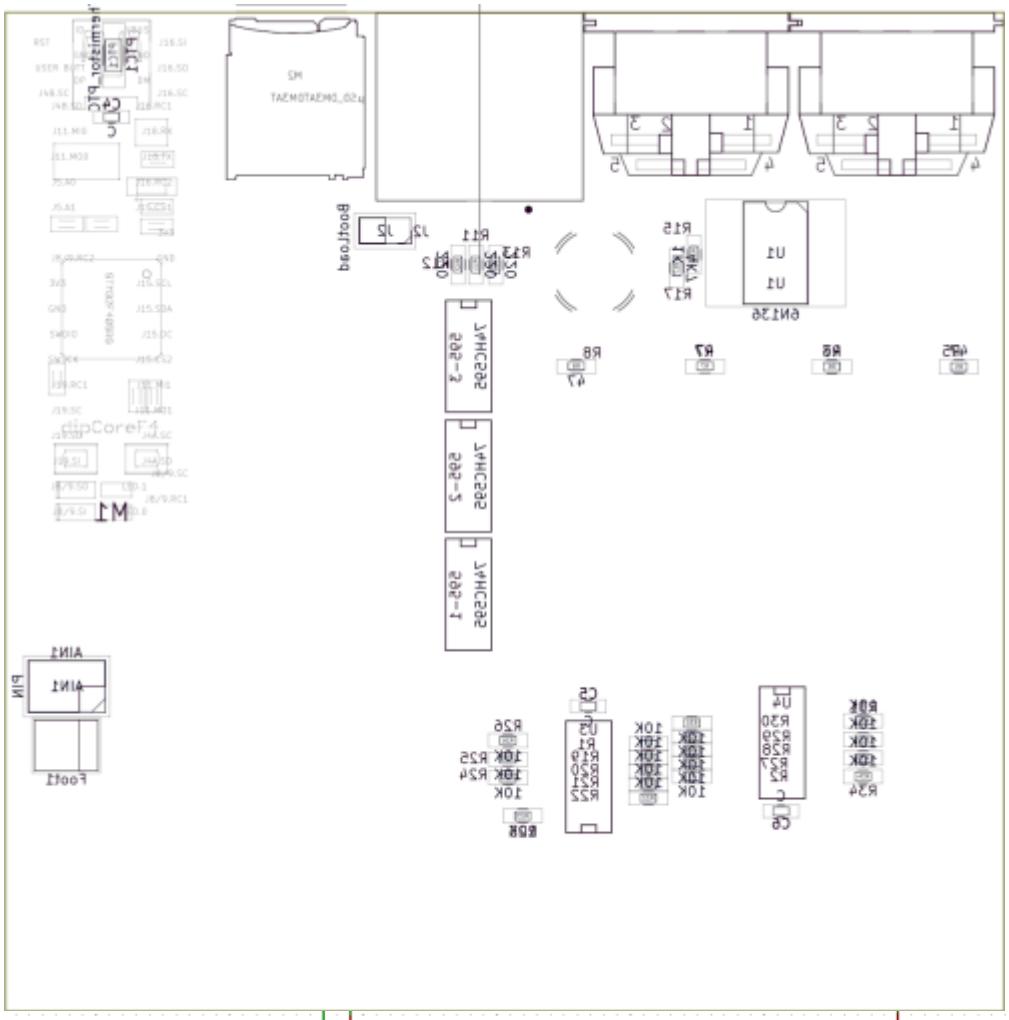
Building

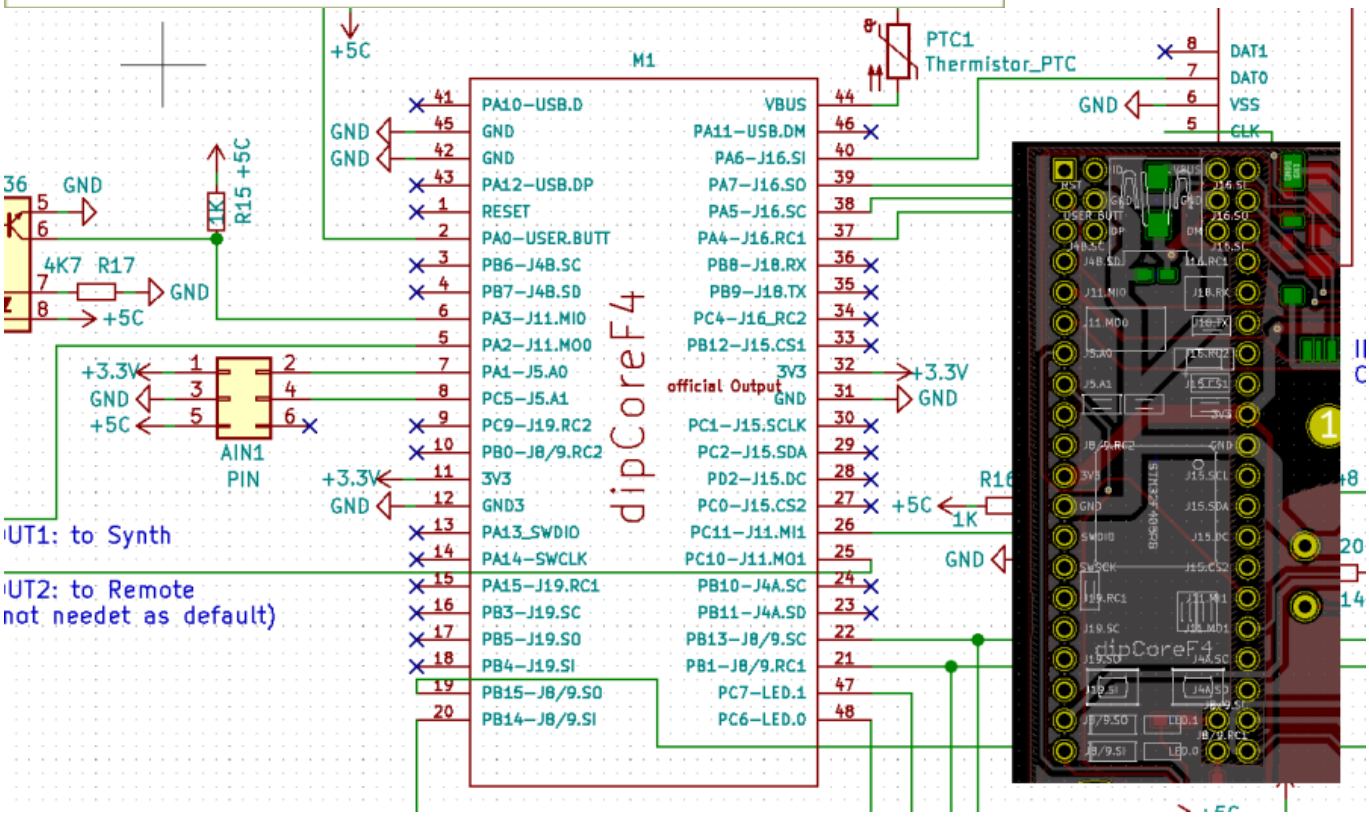


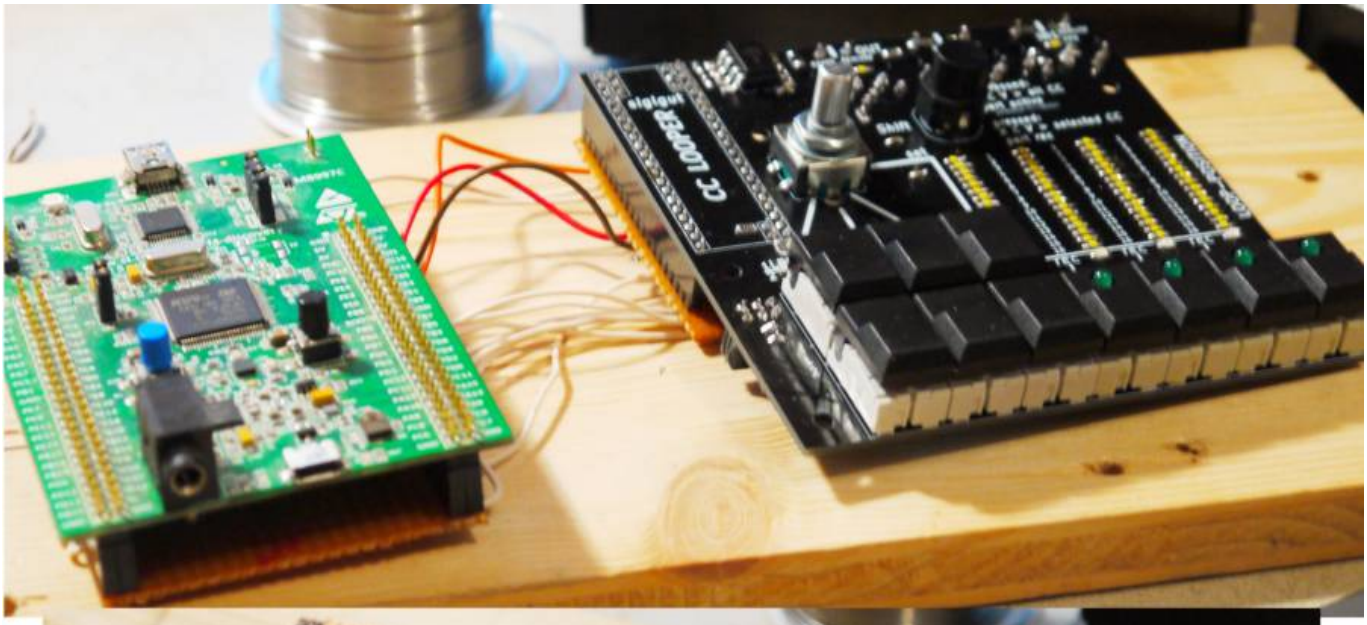

siglgut
CC-LOOPER
unpressed:
pressed:
LOOP-POSITION
LENGTH
Preset
Shift
rec
Part1
Part2
Part3
Part4

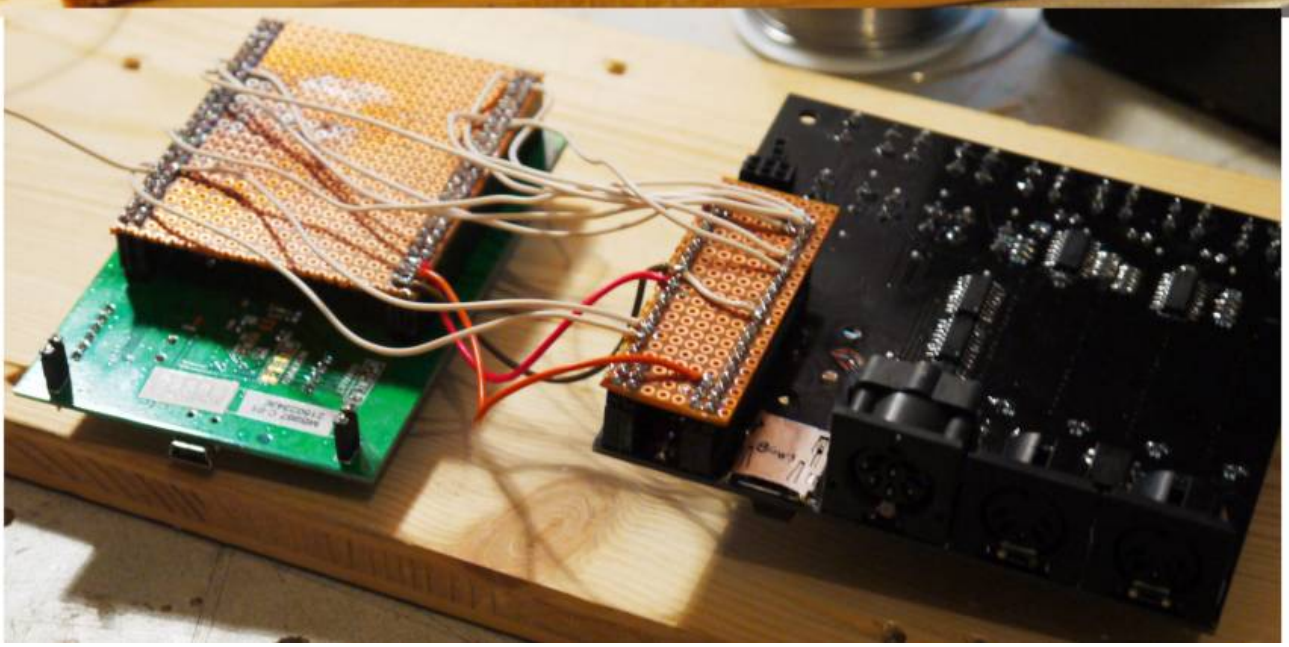

siglgut
CC LOOPER
OUT
synth remote
IN2 synth
IN1 remote seq
unpressed:
X C V > all CC
part active
pressed:
X C V > selected CC
part rec
Shift
set
1LENGTH
2 X
Preset
C
TACT
V
LOOP—POSITION
rec
rec/ Part1
rec/ Part2
rec/ Part3
rec/ Part4
S1
S2
S3
S4
S5
S6
S7
S9
S10
S11

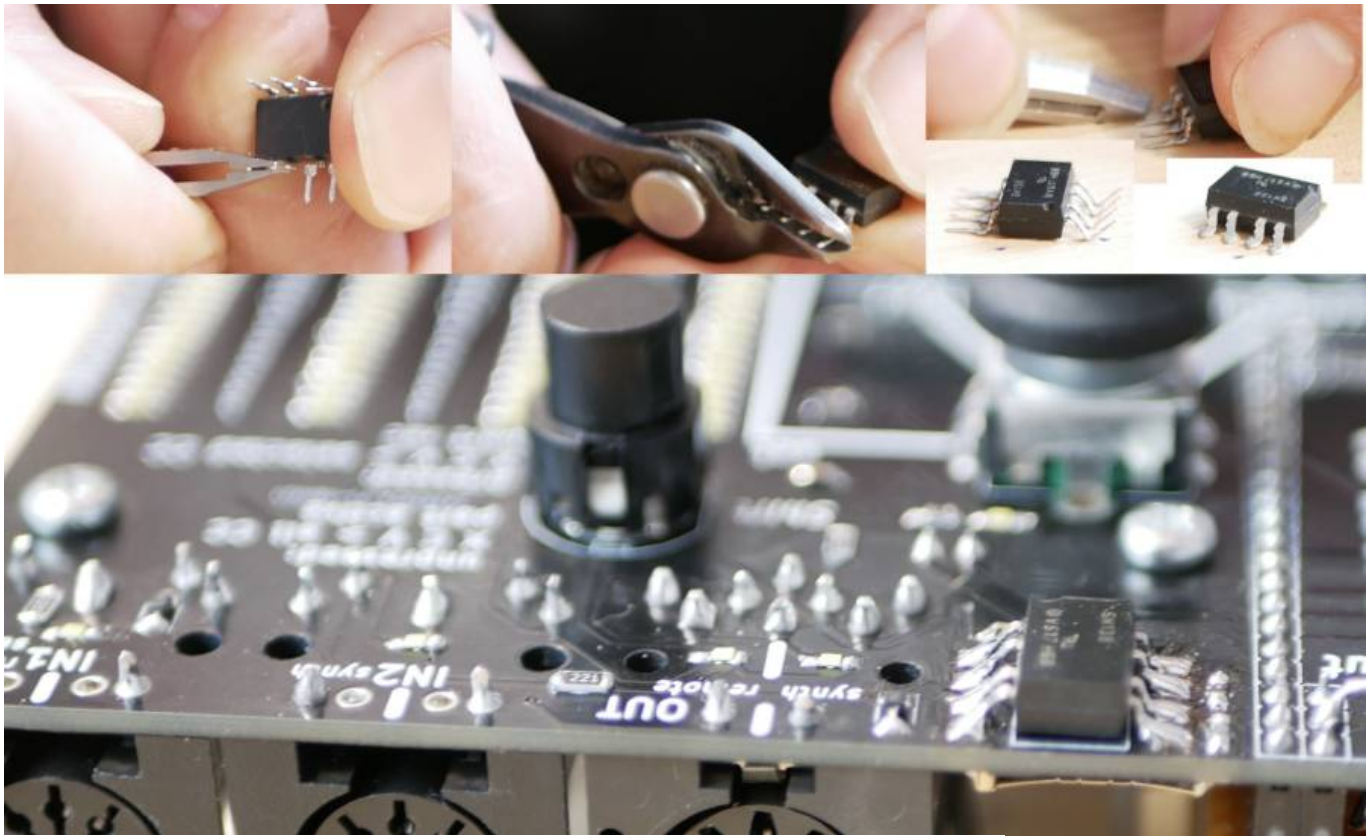

siglgut
CC LOOPER
OUT
synth remote
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IN1 remote seq
unpressed:
X C V > all CC
part active
pressed:
X C V > selected CC
part rec
Shift
set
1LENGTH
2 X
Preset
C
TACT
V
LOOP—POSITION
rec
REC
rec/ Part1
rec/ Part2
rec/ Part3
rec/ Part4
MH1
MH2
MH3
MH4
MH5
hole3,2
S1
S2
S3
S4
S5
S6
S7
S9
S10
S11

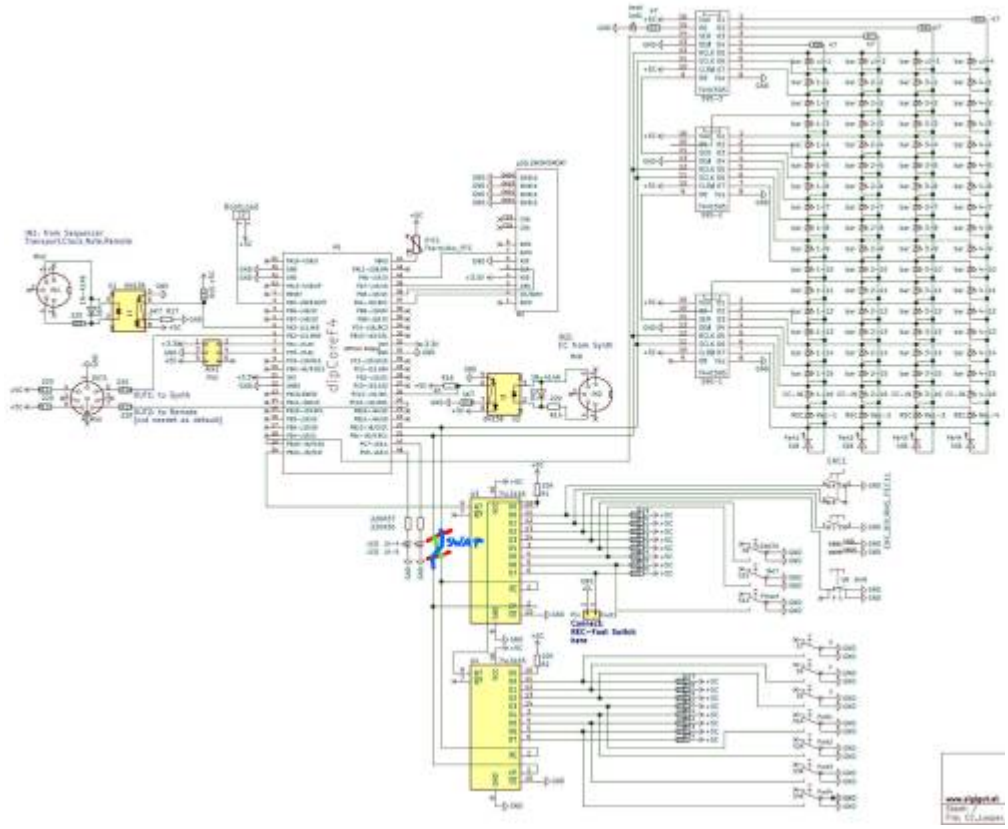


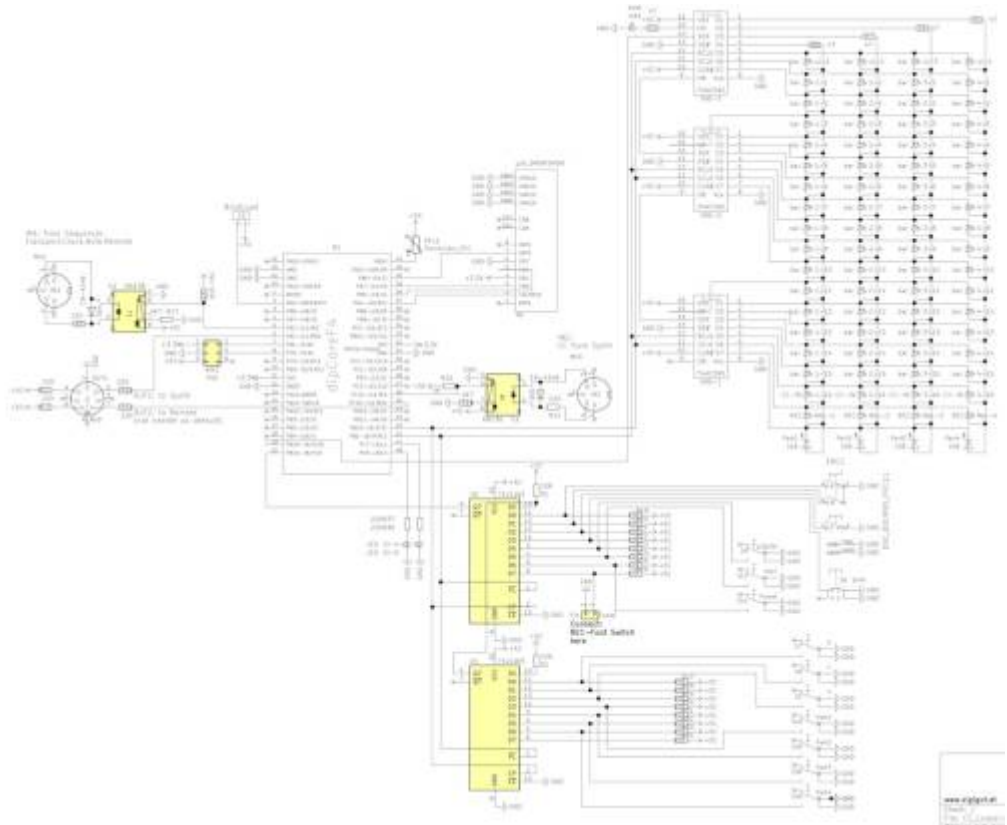

M1
dipCoreF4
PTC1
Thermistor_PTC
+5C
GND
R15 +5C
4K7 R17
AIN1
PIN
official Output
R16
1K
DAT1
DAT0
VSS
CLK
PA10–USB.D
GND
PA12–USB.DP
RESET
PA0–USER.BUTT
PB6–J4B.SC
PB7–J4B.SD
PA3–J11.MI0
PA2–J11.MO0
PA1–J5.A0
PC5–J5.A1
PC9–J19.RC2
PB0–J8/9.RC2
3V3
GND3
PA13_SWDIO
PA14–SWCLK
PA15–J19.RC1
PB3–J19.SC
PB5–J19.SO
PB4–J19.SI
PB15–J8/9.SO
PB14–J8/9.SI
VBUS
PA11–USB.DM
PA6–J16.SI
PA7–J16.SO
PA5–J16.SC
PA4–J16.RC1
PB8–J18.RX
PB9–J18.TX
PC4–J16_RC2
PB12–J15.CS1
3V3
GND
PC1–J15.SCLK
PC2–J15.SDA
PD2–J15.DC
PC0–J15.CS2
PC11–J11.MI1
PC10–J11.MO1
PB10–J4A.SC
PB11–J4A.SD
PB13–J8/9.SC
PB1–J8/9.RC1
PC7–LED.1
PC6–LED.0
UT1: to Synth
UT2: to Remote
not needet as default)

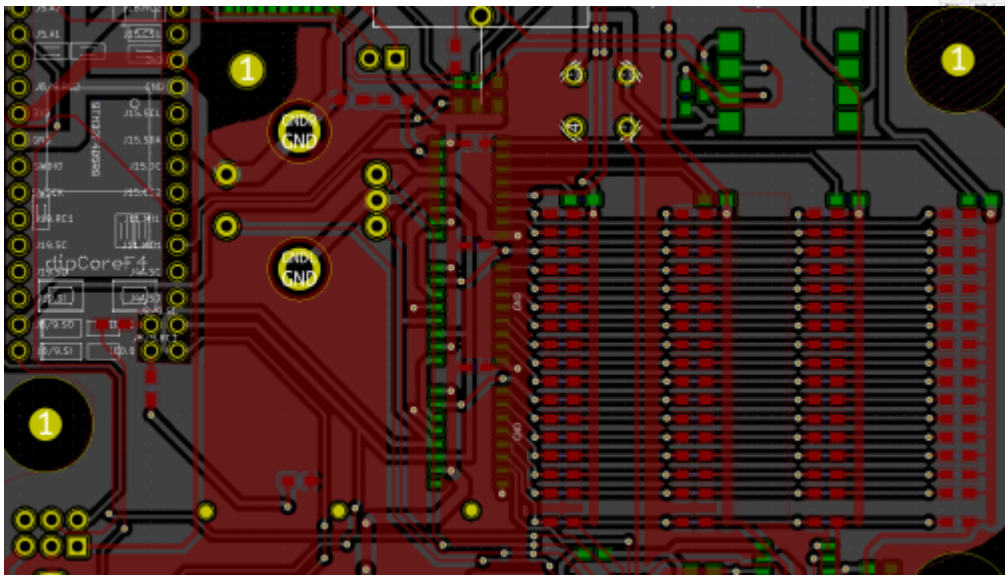

CC LOOPER




OUT
IN2 synth
IN1







Frontpanel

Fix Me! - a clear Acrylic Frontplate, with NO Engravings, UI-Labeling is viewable from PCB

Case

BOM

Ref	Qty	Value	Footprint	MouserPart	
C1 – C7	7	100nF	0603 Capacitor	81-GRM33C71C104ME14D	Mouser
Rec–1 – Rec—4, UI–5 UI—4, led1, -1 -2 -3 -4	11	REC, LED, beat, CC-IN,	0603 LED	630-ASMT-RR45-AQ902	Mouser
1-16 (LED-BAR)	64	bar	0603 LED	755-SMLEN3WBC8W1	Mouser
D64 D65	2	1N-4148	1206 Diode	833-1N4148W-TP	Mouser
PTC1	1	Thermistor_PTC	1206 Resistor	576-1206L150THWR	Mouser
R1, R2, R19 – R34	18	10K	1206 Resistor	603-AC0603FR-0710KL	Mouser
R3 R5 R6 R7 R8	5	47	1206 Resistor	603-RC0603FR-0747RL	Mouser
R9-R14, R36, R37	8	220	1206 Resistor	603-RC0603FR-07220RL	Mouser
R15 R16	2	1K	1206 Resistor	603-RC0603JR-071KL	Mouser
R17 R18	2	4K7	1206 Resistor	603-RC0603FR-074K7L	Mouser
OUT1	1	Midi	DIN-8-SDF-80J	490-SDF-80J	Mouser
M1	1	DIPCORE32_CMPNT_48P	517-929870-01-20-RA	DIP-40	Mouser
S8	1	Shift	DT6	611-D6R00F1LFS	Mouser
S1 – S4	1	Part1	611-SERWHAUOA	DTL2-1-LED	Mouser
S5 – S7, S9 – S10	6	X,C,V,Len,Pre,Tac	611-SERRDAUOA	DTL2-1-NO-LED	Mouser
ENC1	1	ENC_BOURNS_PEC11	ENC_BOURNS_PEC11+SW	652-PEC11R-4215F-S24	Mouser
IN1 IN2	2	Midi	Midi-Socket-MAB5SH-DIN-5	566-MAB5SH	Mouser
Foot1	1	Pin			
J2	1	BootLoad			
AIN1	1	PIN			
U1 U2	2	6N136	SMDIP-8_W11.48mm	782-6N136-X009	Mouser
-595	3	74HC595	SO-16-N	621-74AHC595S16-13	Mouser
U3 U4	2	74LS165	SO-16-N	595-SN74LS165ADR	Mouser
M2	1	µSD_DM3ATDM3AT	MSD_DM3AT	798-DM3AT-SF-PEJM5	Mouser

To Do

alot, beta test, programming the firmware, housing

Resources

KiCad-Dataccl-dipcore.7z
its based on a mixture off:

- msq-cc-lre
- msq-cc-bcr

but its a complete new design, and firmware

Community users working on it

- **Phatline** = Programming, Documentation...

Just let a Private message on the forum to user already involved.
I have 10 ProtoBoards here - i test one, and if it works, i can share them for Beta Testing-if you pay the postage

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